

# On the unilateral contact between two membranes



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## Abstract

In this work, we study the a priori error estimates of the unilateral contact between two elastic membranes. first, we analysis of the continuous problem (the well-posedness of the solution), then we study the reduced discrete problem and its a priori analysis, finally we study the full discrete problem and its a priori analysis.

**Keywords:** unilateral contact, a priori analysis, elastic membranes, discrete problem.

## 1. Modelization

From the fundamental laws of elasticity, we write a model for the contact between two membranes. The contact is taken into account according to the following principles:

(i) The two membranes cannot interpenetrate. (ii) Where they are in contact, owing to Newton's action-reaction law, each membrane has an action on the other. An elastic membrane is characterized by its displacement  $u$  with respect to its natural configuration which is a two dimensional domain  $\omega$ . The equilibrium position of the membrane, under the action of a vertical force  $\mathcal{F}$  minimizes the potential energy functional:

$$J : v \rightarrow J(v) = \frac{1}{2} \int_{\omega} \mu(x) |\nabla v(x)|^2 dx - \int_{\omega} \mathcal{F}(x) v(x) dx \quad (1.1)$$

The minimization problem reads that's;

$$\text{Find } u \in H_0^1(\omega) \text{ such that } \forall v \in H_0^1(\omega); J(u) \geq J(v) \quad (1.2)$$

or equivalent :

$$\begin{cases} -\text{div}(\mu \nabla u) = \mathcal{F} & \text{in } \omega, \\ u = 0 & \text{on } \partial\omega \end{cases} \quad (1.3)$$

More details can be found in [1], Chapter 1, Section 1.2, for instance. Let us now consider two elastic membranes: The first is fixed on  $\partial\omega$  at the height  $g$ . Where  $g$  is a nonnegative function, and the second one is fixed at zero. the corresponding system of equation reads with obvious notation,

$$\begin{cases} -\text{div}(\mu_1 \nabla u_1) = \mathcal{F}_1 & \text{in } \omega, \\ u_1 = g & \text{on } \partial\omega \end{cases} \quad \begin{cases} -\text{div}(\mu_2 \nabla u_2) = \mathcal{F}_2 & \text{in } \omega, \\ u_2 = 0 & \text{on } \partial\omega \end{cases} \quad (1.4)$$

We are interested in the case where the membranes interact. Therefore, if  $\lambda$  represents the action of the second membrane on the first one, we have  $\mathcal{F}_1 = f_1 + \lambda$ ,  $\mathcal{F}_2 = f_2 + \lambda$ , where the  $f_i$  are external forces. It's follows from the definition of  $\lambda$  that :  $\lambda \geq 0$  in  $\omega$ . Moreover, clearly the two membranes cannot interpenetrate. This yields the conditions  $u_1 - u_2 \geq 0$  in  $\omega$ . Finally, we note that, where the membranes are not in contact, i.e., where  $u_1 - u_2 > 0$ , the interaction  $\lambda$  vanishes. This leads to the equation  $(u_1 - u_2)\lambda = 0$  in  $\omega$ . We are interested in the analysis of this system.

## 2. Analysis of the continuous problem

Let  $\omega$  be a bounded open set in  $\mathbb{R}^2$  with a Lipschitz-continuous boundary, we consider the following system:

$$\begin{cases} -\mu_1 \Delta u_1 - \lambda = f_1 & \text{in } \omega, \\ -\mu_2 \Delta u_2 + \lambda = f_2 & \text{in } \omega, \\ u_1 - u_2 \geq 0, \lambda \geq 0, (u_1 - u_2)\lambda = 0 & \text{in } \omega, \\ u_1 = g, u_2 = 0 & \text{on } \partial\omega. \end{cases} \quad (2.1)$$

we consider the following full scales of Sobolev spaces :

$H_0^1(\omega) = \{v \in H^1(\omega); v = 0 \text{ on } \partial\omega\}$ ;  $V = \{v \in H^1(\omega); v \geq 0\}$ . and  $\Lambda = \{\chi \in L^2(\omega); \chi \geq 0 \text{ a.e in } \omega\}$ . So we introduce the following variational problem, for any data  $(f_1, f_2) \in H^{-1}(\omega) \times H^{-1}(\omega)$  and  $g \in H_0^1(\partial\omega)$ : Find  $(u_1, u_2, \lambda) \in H_0^1(\omega) \times H_0^1(\omega) \times \Lambda$  such that

$$\begin{cases} \forall (v_1, v_2) \in H_0^1(\omega) \times H_0^1(\omega), \\ \sum_{i=1}^2 \mu_i \int_{\omega} \nabla u_i(x) \cdot \nabla v_i(x) dx - \int_{\omega} \lambda(x) (v_1 - v_2)(x) dx = \sum_{i=1}^2 \langle f_i, v_i \rangle \\ \forall \chi \in \Lambda, \int_{\omega} (\chi - \lambda)(x) (u_1 - u_2)(x) dx \geq 0 \end{cases} \quad (2.2)$$

**Proposition 2.1 :** Problems (2.1) and (2.2) are equivalent

We introduce the new non empty ( $g \geq 0 \implies g \in K_g$ ) convex set :

$$K_g = \{(v_1, v_2) \in H_0^1(\omega) \times H_0^1(\omega); v_1 - v_2 \geq 0 \text{ a.e. in } \omega\}. \quad (2.3)$$

We then consider the reduced problem : find  $(u_1, u_2) \in K_g$  such that

$$\forall (v_1, v_2) \in K_g, \sum_{i=1}^2 \mu_i \int_{\omega} \nabla u_i(x) \cdot \nabla (v_i - u_i)(x) dx \geq \sum_{i=1}^2 \langle f_i, v_i - u_i \rangle. \quad (2.4)$$

**Lemma 2.2 :** For any solution  $(u_1, u_2, \lambda)$  of (2.2), the pair  $(u_1, u_2)$  is solution of problem (2.4).

**Proposition 2.3 :** for any data  $(f_1, f_2) \in H^{-1}(\omega)^2$  and  $g \in H_0^1(\partial\omega)$ , the problem (2.4) has a unique solution. For proving this, we take  $v_- = \min\{v, 0\}$  in  $H^1(\omega)$  and using the Lions-Stampacchia theorem.

**Theorem 2.4 :** for any data  $(f_1, f_2) \in H^{-1}(\omega)^2$  and  $g \in H_0^1(\partial\omega)$ , the problem (2.2) has a unique solution  $(u_1, u_2, \lambda) \in H_0^1(\omega) \times H_0^1(\omega) \times \Lambda$ .

**Corollary 2.5 :** for any data  $(f_1, f_2) \in L^2(\omega)^2$  and  $g \in H_0^1(\partial\omega)$ , the solution  $(u_1, u_2, \lambda)$  of problem (2.2) satisfies

$$\|u_1\|_{H^1(\omega)} + \|u_2\|_{H^1(\omega)} + \|\lambda\|_{L^2(\omega)} \leq c(\|f_1\|_{L^2(\omega)} + \|f_2\|_{L^2(\omega)} + \|g\|_{H_0^1(\partial\omega)}) \quad (2.5)$$

## 3. A priori analysis of the problem

### 3.1 The reduced discrete problem and its a priori analysis

we that  $w$  is a polygonal. Let  $\mathcal{T}_h$  be a regular family triangulations of  $w$ . We will use the discrete spaces given as:

$$\mathbb{X}_h = \{v_h \in H^1(w); \forall K \in \mathcal{T}_h, v_h|_K \in \mathcal{P}_1\}$$

$\mathbb{X}_{0h} = \mathbb{X}_h \times H_0^1(w)$  and  $\mathbb{X}_{gh} = \mathbb{X}_h \times H_g^1(w)$  then  $\mathbb{X}_{gh} = \{(v_1 - v_2) \in \mathbb{X}_{gh}; (v_1 - v_2) \geq 0 \text{ in } w\}$ . by the Galerkin method we have the reduced discrete problem which is has a unique solution  $(u_{1h}, u_{2h}) \in K_{gh}$  such that :

$$\forall (v_{1h}, v_{2h}) \in K_{gh}, \sum_{i=1}^2 \mu_i \int_{\omega} \nabla u_{ih}(x) \cdot \nabla (v_{ih} - u_{ih})(x) dx \geq \sum_{i=1}^2 \langle f_i, v_{ih} - u_{ih} \rangle. \quad (3.1)$$

**Theorem 3.1** assume that  $w$  is convex, that  $(f_1, f_2) \in (L^2(w))^2$  and  $g \in H_0^1(\partial w)$  then we obtain the a priori error estimats between the solution of  $(u_1, u_2)$  of problem (2.4) and  $(u_{1h}, u_{2h})$  of problem (3.1) :

$$\|u_1 - u_{1h}\|_{H^1(w)} + \|u_2 - u_{2h}\|_{H^1(w)} \leq Ch \left( \|f_1\|_{L^2(w)} + \|f_2\|_{L^2(w)} + \|g\|_{H_0^1(\partial w)} \right). \quad (3.2)$$

### 3.2 construction of the discrete action by local postprocessing

Let  $\mathcal{V}_h$  denote the set of elements of  $\mathcal{T}_h$  wich not belong to  $\partial w$ . we define the Lagrange functions associated with  $a \in \mathcal{V}_h$  by  $\varphi_a \in \mathbb{X}_{0h}$  satisfis  $\varphi_a(a) = 1$  and  $\forall a' \in \mathcal{V}_h, a' \neq a, \varphi_a(a') = 0$ . We denote  $\mathcal{T}_h = \{K_h \in \mathcal{T}_h, a \in K_h\}$ ;  $h_a = \max_{K \in \mathcal{T}_h} \{\text{diam} K\}$ ;

where  $\Delta_a = \text{supp}(\varphi_a)$ , and the nonnegative functions  $\chi_a \in L^2(w)$  with asupport in a neighbourhood of  $a$ , and define  $\mathbb{Y}_h$  space spanned with this functions if  $\chi_a$  linearly independant so that :  $\dim \mathbb{Y}_h = \dim \mathbb{X}_{0h}$ , the next convex set

$$\Lambda_h = \{\rho_h = \sum_{a \in \mathcal{V}_h} \rho_a \chi_a; \rho_a \geq 0\} \subset \Lambda.$$

we introduce a duality pairing between  $\mathbb{Y}_h$  and  $\mathbb{X}_h$  by

$$\langle \rho_h, v_h \rangle_h = \sum_{a \in \mathcal{V}_h} \rho_a \varphi_a(a) \int_{K \in \mathcal{T}_h} \int_K \varphi_a(x) dx.$$

$$\langle \rho_h, v_h \rangle_h = \sum_{a \in \mathcal{V}_h} \rho_a \varphi_a(a) \int_{K \in \mathcal{T}_h} \int_K \varphi_a(x) dx.$$

with the same notation we have the previous definition;

$$\langle \rho_h, \varphi_a \rangle_h = \rho_a \int_{K \in \mathcal{T}_h} \int_K \varphi_a(x) dx.$$

then we can define the functions  $\lambda_{1h}$  and  $\lambda_{2h}$  in  $\mathbb{Y}_h$ , where  $v_{1h}, v_{2h} \in \mathbb{X}_{0h}$ .

$$\begin{cases} \langle \lambda_{1h}, v_{1h} \rangle_h = \mu_1 \int_{\omega} \nabla u_{1h}(x) \cdot \nabla v_{1h}(x) dx - \langle f_1, v_{1h} \rangle \\ \langle \lambda_{2h}, v_{2h} \rangle_h = -\mu_2 \int_{\omega} \nabla u_{2h}(x) \cdot \nabla v_{2h}(x) dx + \langle f_2, v_{2h} \rangle \end{cases} \quad (3.3)$$

**Proposition 3.2** the functions  $\lambda_{1h}$  and  $\lambda_{2h}$  are coincide.

In view of the last proposition, we now write a discrete problem of the problem (2.2) by the Galerkin methode. It reads : find  $(u_{1h}, u_{2h}, \lambda_h) \in \mathbb{X}_{gh} \times \mathbb{X}_{0h} \times \Lambda_h$  such that

**Proposition 3.3**

$$\begin{cases} \forall (v_{1h}, v_{2h}) \in \mathbb{X}_{0h} \times \mathbb{X}_{0h}; \\ \sum_{i=1}^2 \mu_i \int_{\omega} \nabla u_{ih}(x) \cdot \nabla v_{ih}(x) dx - \langle \lambda_{1h}, v_{1h} - v_{2h} \rangle_h = \sum_{i=1}^2 \langle f_i, v_{ih} \rangle \\ \forall \chi \in \Lambda_h; \langle \lambda_{1h} - \lambda_{2h}, u_{1h} - u_{2h} \rangle_h \geq 0 \end{cases} \quad (3.4)$$

**Lemma 3.4 :** For any solution  $(u_{1h}, u_{2h}, \lambda_h)$  of (3.3), the pair  $(u_{1h}, u_{2h})$  is solution of problem (3.1), and the conversely.

**Theorem 3.5**  $\forall (f_1, f_2) \in (L^2(w))^2$  and  $g \in H_0^1(\partial w)$ ,  $s \geq 0$ , the problem (3.3) has a unique solution  $(u_{1h}, u_{2h}, \lambda_h) \in \mathbb{X}_{gh} \times \mathbb{X}_{0h} \times \Lambda_h$ .

**Theorem 3.6** we have the following a priori error estimate of action

$$\|\lambda - \lambda_h\|_{H^{-1}(\omega)} \leq Ch \left( \|f_1\|_{L^2(\omega)} + \|f_2\|_{L^2(\omega)} + \|g\|_{H_0^1(\partial\omega)} \right)$$

## 4. Conclusion

we propose a standard finite element discretization of the variational formulation constructed by the Galerkin method with Lagrange finite elements. We prove that the discrete problem has a unique solution and derive optimal a priori error estimates. The discretization of the full problem relies on the reduced discrete problem but is more complex.

## 5. Perspective

We hope to study the a priori error estimates of the unilateral contact between two plates, together with some numerical experiments.

## References

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